

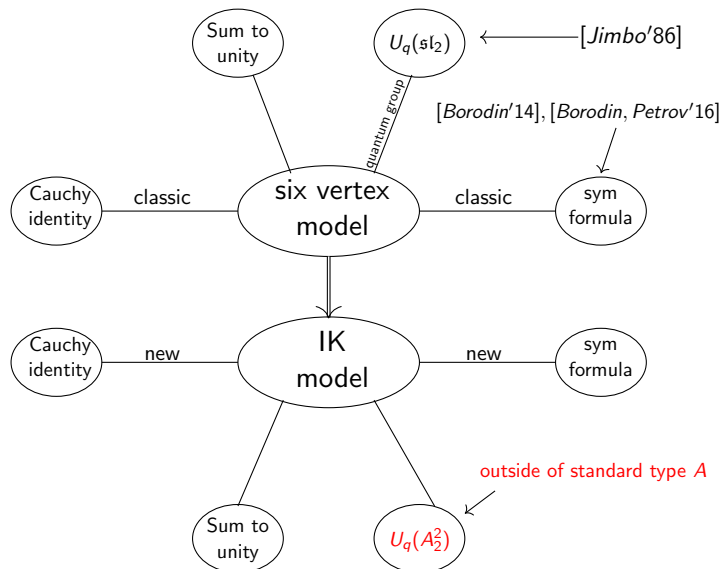
Rational symmetric functions from the Izergin–Korepin 19-vertex model

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Motivations



Izergin–Korepin model

Izergin–Korepin model [Izergin, Korepin'81] has weights

$$W_{y/x}(i, j; k, \ell) := \begin{array}{c} \begin{array}{c} \uparrow k \\ \hline x \rightarrow j \hline \downarrow i \\ \uparrow y \end{array} \end{array} \quad \text{where } i, j, k, \ell \in \{0, 1, 2\}.$$

Example

$$\begin{array}{c} 2 \\ \uparrow \\ 0 \rightarrow 0 \\ \downarrow \\ 2 \end{array} = \frac{q^4(x-y)(x-xy)}{(x-q^2y)(x-q^3y)}$$

$$\begin{array}{c} 0 \\ \uparrow \\ 2 \rightarrow 2 \\ \downarrow \\ 0 \end{array} = \frac{(x-y)(x-xy)}{(x-q^2y)(x-q^3y)}$$

Izergin–Korepin model

Izergin–Korepin model [Izergin, Korepin'81] has weights

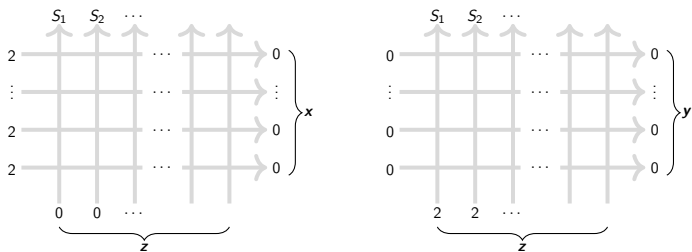
$$W_{y/x}(i, j; k, \ell) := \begin{array}{c} \begin{array}{c} \text{---} x \rightarrow j \text{---} \\ \uparrow \\ k \\ \uparrow \\ \text{---} \ell \text{---} \\ \downarrow \\ i \\ \downarrow \\ y \end{array} \end{array} \quad \text{where } i, j, k, \ell \in \{0, 1, 2\}.$$

The Yang–Baxter equation is

The diagram illustrates the Yang–Baxter equation for the Izergin–Korepin model. It shows two equivalent configurations of three lines labeled x , y , and z . On the left, lines x and y cross, and line z passes through a crossing of dashed lines. On the right, lines x and y cross, and line z passes through a crossing of dashed lines. The two configurations are separated by an equals sign.

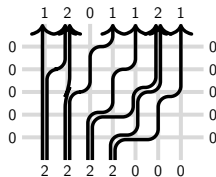
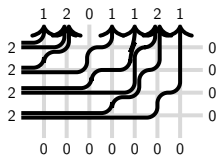
Rational function (Izergin–Korepin model)

The rational functions $F_S(\mathbf{x}; \mathbf{z})$ (left panel) and $G_S(\mathbf{y}; \mathbf{z})$ (right panel) are



where $S = (S_1, S_2, \dots)$ and $S_i \in \{0, 1, 2\}$.

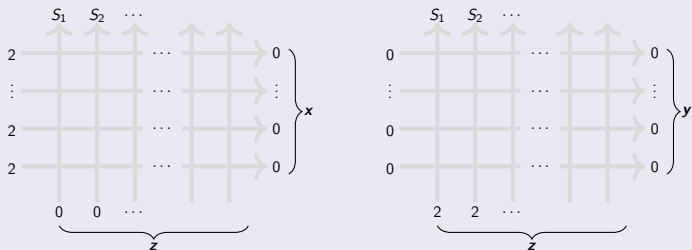
Example:



Rational function (Izergin–Korepin model)

Definition

The rational functions $F_S(\mathbf{x}; \mathbf{z})$ (left panel) and $G_S(\mathbf{y}; \mathbf{z})$ (right panel) are



where $S = (S_1, S_2, \dots)$ and $S_i \in \{0, 1, 2\}$.

Theorem

The partition functions $F_S(\mathbf{x}; \mathbf{z})$ and $G_S(\mathbf{y}; \mathbf{z})$ are symmetric in \mathbf{x} and \mathbf{y} .

Domain-wall partition function (Izergin–Korepin model)

Definition

The domain-wall partition function [Garbali'15] is

$$F_{(2^N)}(\mathbf{x}; \mathbf{z}) :=$$

Taking $\mathbf{z} \rightarrow \infty$, the partition function becomes

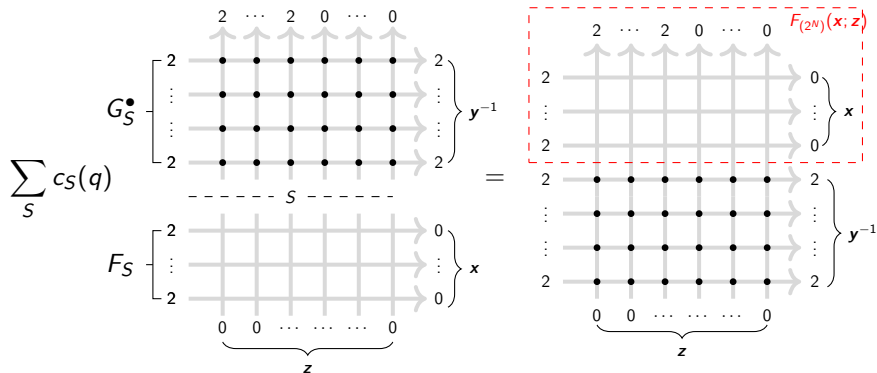
$$Z_N(q) := \lim_{\mathbf{z} \rightarrow \infty} F_{(2^N)}(\mathbf{x}; \mathbf{z}) = \left(\prod_{i=1}^N 1 - q^{-2i} \right) \left(\prod_{j=1}^N 1 + q^{-2j+1} \right).$$

Cauchy identity (Izergin–Korepin model)

The Izergin–Korepin Cauchy identity is given by

$$\sum_S c_S(q) F_S(\mathbf{x}; \mathbf{z}) G_S(\mathbf{y}; (q^3 \mathbf{z})^{-1}) = F_{(2^N)}(\mathbf{x}; \mathbf{z}) \prod_{i,j} \frac{(1 - q^2 x_i y_j)(1 - q^3 x_i y_j)}{(1 - x_i y_j)(1 - q x_i y_j)}.$$

The pictorial presentation is



Stable rational function (Izergin–Korepin model)

Definition

The *stable rational functions* are defined by

$$H_S(\mathbf{x}; \mathbf{z}) := \frac{1}{Z_{|\mathbf{u}|}(q)} \lim_{\mathbf{u} \rightarrow \infty} F_S(\mathbf{x}; \mathbf{u} \cup \mathbf{z}).$$

Theorem

The rational function H_S satisfies the *stability* property

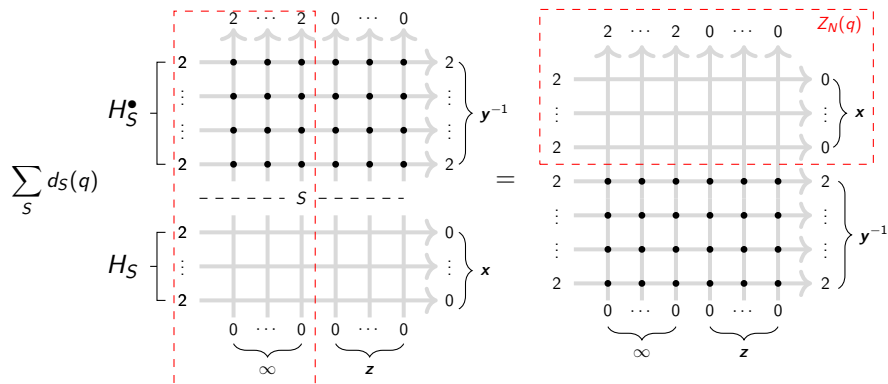
$$H_S(x_1, x_2, \dots, x_N = \infty; \mathbf{z}) = \begin{cases} H_S(x_1, x_2, \dots, x_{N-1}; \mathbf{z}) & |S| < 2N - 2, \\ 0 & \text{otherwise.} \end{cases}$$

Cauchy identity for stable functions

The Cauchy identity simplifies

$$\sum_S d_S(q) H_S(\mathbf{x}; \mathbf{z}) H_S(\mathbf{y}; (q^3 \mathbf{z})^{-1}) = \prod_{i,j} \frac{(1 - q^2 x_i y_j)(1 - q^3 x_i y_j)}{(1 - x_i y_j)(1 - q x_i y_j)}.$$

The pictorial presentation is

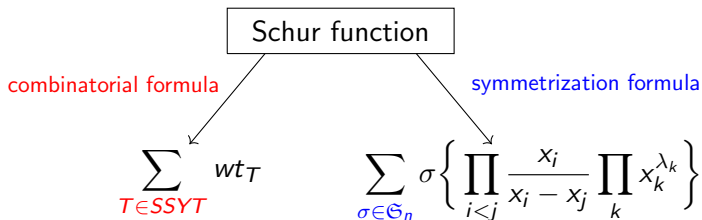


Symmetrization formula (Izergin–Korepin model)

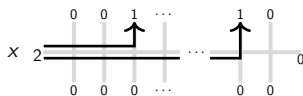
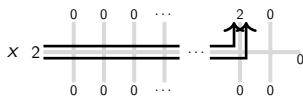
What is a symmetrization formula?

- An explicit form of $F_S(\mathbf{x}; \mathbf{z})$
- Easy to compute and digest

For example,

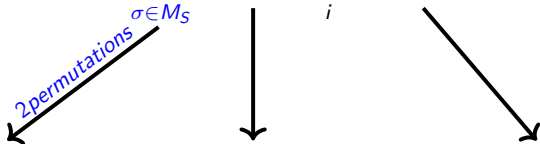


- One row partition functions



Symmetrization formula (Izergin–Korepin model)

$$F_S(\mathbf{x}; \mathbf{z}) = \sum_{\sigma \in M_S} \Delta_{\sigma}(\mathbf{x}; \mathbf{z}) \prod_i F_{\sigma(i)}(\mathbf{x}; \mathbf{z})$$



$$S = (2^2), \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$$

$$S = (2^3), \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 2 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 2 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 2 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 2 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 0 & 2 & 0 \\ 0 & 0 & 2 \\ 2 & 0 & 0 \end{pmatrix}$$

$$\vdots$$

Symmetrization formula (Izergin–Korepin model)

$$F_S(\mathbf{x}; \mathbf{z}) = \sum_{\sigma \in M_S} \Delta_{\sigma}(\mathbf{x}; \mathbf{z}) \prod_i F_{\sigma(i)}(\mathbf{x}; \mathbf{z})$$

↙ ↓ ↘
2 permutations scattering factor one row functions

$$S = (2^2), \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$$

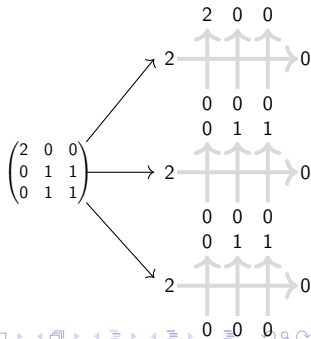
$$S = (2^3), \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 2 \\ 0 & 2 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 2 \\ 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 2 & 0 \\ 2 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 2 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 0 & 2 & 0 \\ 0 & 0 & 2 \\ 2 & 0 & 0 \end{pmatrix}$$

next page !



Scattering factor

- $\Delta_\sigma(\mathbf{x}; \mathbf{z})$ is a rational function
- $\Delta_\sigma(\mathbf{x}; \mathbf{z})$ is a product of pairs of rows

List of all factors

$$\Delta_{V,U}(x_i, x_j; z) = \left\{ \begin{array}{l} \frac{(q^2 x_i - x_j)(q^3 x_i - x_j)}{(x_i - x_j)(qx_i - x_j)}, \quad \frac{U \parallel \mid 2}{V \parallel 2 \mid}, \quad \frac{U \parallel \mid 1 \mid 1}{V \parallel 2 \mid}, \quad \frac{U \parallel \mid 2}{V \parallel 1 \mid 1}, \quad \frac{U \parallel \mid 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(x_i - q^2 x_j)(x_i - q^3 x_j)}{(x_i - x_j)(x_i - qx_j)}, \quad \frac{U \parallel 2}{V \parallel 2 \mid}, \quad \frac{U \parallel 2}{V \parallel 1 \mid 1}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 2 \mid}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_i - x_j)(x_i - q^2 x_j)}{(x_i - x_j)^2}, \quad \frac{U \parallel 2}{V \parallel 1 \mid}, \quad \frac{U \parallel 1}{V \parallel 2 \mid}, \quad \frac{U \parallel 1}{V \parallel 1 \mid 1}, \quad \frac{U \parallel 1}{V \parallel 1 \mid 1}, \quad \frac{U \parallel 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_i - x_j)^2(qx_j - x_i)}{(x_i - x_j)^2(qx_i - x_j)}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(qx_i - x_j)(x_i - q^2 x_j)^2}{(qx_j - x_i)(x_i - x_j)^2}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}. \end{array} \right.$$

$$\Delta_{V,U}(x_i, x_j; z) = \left\{ \begin{array}{l} \frac{(q^2 x_i - x_j)(x_i x_j + q^2 x_i x_j - q^3 x_i z_{s_1} - q^3 x_j z_{s_1})}{q(-1+q)z_{s_1}(x_i - x_j)(x_j - qx_i)}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_j - x_i)(x_i x_j + q^2 x_i x_j - q^3 x_i z_{s_1} - q^3 x_j z_{s_1})}{q(-1+q)z_{s_1}(x_i - x_j)(qx_j - x_i)}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_i - x_j)(x_i x_j + q^2 x_i x_j - q^2 x_i z_{s_2} - q^2 x_j z_{s_2})}{(-1+q)(x_i - x_j)(x_j - qx_i)z_{s_2}}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_j - x_i)(x_i x_j + q^2 x_i x_j - q^2 x_i y_{s_2} - q^2 x_j y_{s_2})}{(-1+q)(x_i - x_j)(qx_j - x_i)z_{s_2}}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_i - x_j)(x_i x_j + q^2 x_i x_j - q^3 x_i z_{s_2} - q^3 x_j z_{s_2})}{q(-1+q)(x_i - x_j)^2 z_{s_2}}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}, \\ \frac{(q^2 x_j - x_i)(x_i x_j + q^2 x_i x_j - q^2 x_i z_{s_1} - q^3 x_j z_{s_1})}{q(-1+q)(x_i - x_j)^2 z_{s_1}}, \quad \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}. \end{array} \right.$$

$$\Delta_{V,U}(x_i, x_j; z) = \frac{(x_i x_j + q^2 x_i x_j - q^3 x_i z_{s_1} - q^3 x_j z_{s_1})(x_i x_j + q^2 x_i x_j - q^2 x_i z_{s_2} - q^2 x_j z_{s_2})}{q(-1+q)^2(x_j - qx_i)(x_i - qx_j)z_{s_1}z_{s_2}} \frac{U \parallel 1 \mid 1}{V \parallel 1 \mid 1}$$

In this talk, we have discussed

- The rational functions F_S and G_S for the Izergin–Korepin model
- The Cauchy identity for the rational functions F_S and G_S
- The symmetrization formula for the rational functions F_S

Future directions

- Generalize to higher spin (fusion)
- Possibility of “coloured” Izergin–Korepin model [Borodin, Wheeler’18]
- Orthogonality of the rational functions F_S [Borodin, Petrov’16]
- K -matrix for the boundary of the Izergin–Korepin model